

# ROBODoc System Tests

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# 1 ROBODOc/ROBODOc System Tests

## FUNCTION

A set of perl scripts that test ROBODOc functionality. Each script contains one or more system tests. Each test starts ROBODOc with a specific input and then asserts that ROBODOc produces the correct output.

The tests use the Perl unittest framework, that is the modules:

- Test::More, See <http://perldoc.perl.org/Test/More.html>
- Test::File

There is also a custom module ROBOTestFrame (2) that contains a set of useful functions that are common to all tests.

You can run the tests with

```
prove
```

Tests go into files with the extension `.t`. You can run an individual set of tests with

```
prove <testfile>
```

A 'prove' should always result in a 100% score. No test should fail.

## 1.1 ROBODOc System Tests/Basics

### FUNCTION

Tests basic ROBODOc functionality. These are all 'happy paths'.

### 1.1.1 Basics/Dummy Headers

#### FUNCTION

A dummy header to put into dummy source files.

#### SOURCE

```
my $source = <<'EOF';  
/****f* Test/test  
* NAME  
* Test  
*****  
*/  
EOF
```

### 1.1.2 Basics/One file per header

#### FUNCTION

Test `-multidoc` with `-one_file_per_header` for html output. We test this with one source file that contains three headers. These should result in three documentation files. To make it nasty we use some special header names.

#### SOURCE

```
#    A dummy header to put into dummy source files.
my $source = <<'EOF';
/****f* Test/Test
 * NAME
 *   Test foo bar
 * ****
 */

/****f* Test/foo, bar
 * NAME
 *   Test foo bar
 * ****
 */

/****f* Test/aa::awaw
 * NAME
 *   Test foo bar
 * ****
 */

EOF

{
  add_source( "test.c", $source );
  my ( $out, $err ) = runrobo(qw(--src Src --doc Doc --one_file_per_header --multidoc --html));
  # expected results:
  is( $out, '', 'No output' );
  is( $err, '', '... and no error' );
  # There are three headers, so there should be three documentation files.
  file_exists_ok( 'Doc/test_cTest2FTest.html',      'Documentation for Test/Test' );
  file_exists_ok( 'Doc/test_cTest2Ffoo.html',      'Documentation for Test/foo' );
  file_exists_ok( 'Doc/test_cTest2Faa3A3Aawaw.html', 'Documentation for Test/aa::awaw' );
  # And a style sheet.
  file_exists_ok( "Doc/robodoc.css", 'and a stylesheet' );
  clean();
}
```

### 1.1.3 Basics/Option help

#### FUNCTION

Test the option -help.

#### SOURCE

```
{  
  my ( $out, $err ) = runrobo('--help');  
  like( $out, qr/ROBODoc Version/, '--help should print version number' );  
  is( $err, '', '... and no error' );  
}
```

### 1.1.4 Basics/Option multidoc

#### FUNCTION

Test `--multidoc` for html output format. (Multidoc for other modes does not make much sense). We create one source file with a simple header and create multidoc

#### SOURCE

```
{
  add_source( "test.c", $source );
  my ( $out, $err ) = runrobo(qw(--src Src --doc Doc --multidoc --html));
  # expected results:
  is( $out, '', 'No output' );
  is( $err, '', '... and no error' );
  file_exists_ok( "Doc/test_c.html", 'there should be documentation' );
  file_exists_ok( "Doc/robodoc.css", 'and a stylesheet' );

  clean();
}
```



### 1.1.5 Basics/Option version

#### FUNCTION

Test robodoc --version, this should report the current version.

#### SOURCE

```
{  
  my ( $out, $err ) = runrobo('--version');  
  like( $out, qr/\d+\.\d+\.\d+/, '--version should print version number' );  
  is( $err, '', '... and no error' );  
}
```

### 1.1.6 Basics/Singledoc Outputmode with Different Formats

#### FUNCTION

Test singledoc mode for all supported output formats and see if it creates output in this format.

#### SOURCE

```
{
  add_source( "test.c", $source );

  my %output_modes = (
    '--html' => 'html',
    '--rtf'  => 'rtf',
    '--test' => 'xml',
    '--latex' => 'tex',
    '--dbxml' => 'xml',
  );

  foreach my $mode ( keys %output_modes ) {
    my $file_extension = $output_modes{$mode};

    my @arguments = qw(--src Src --doc testdoc --singledoc);
    push( @arguments, $mode );

    my ( $out, $err ) = runrobo(@arguments);
    is( $out, '', 'No output' );
    is( $err, '', '... and no error' );
    file_exists_ok( "testdoc.$file_extension",
      'there should be documentation' );
    if ( $mode eq "--html" ) {
      file_exists_ok( "testdoc.css", 'and a stylesheet' );
    }

    unlink("testdoc.$file_extension") if -e "testdoc.$file_extension";
    unlink('testdoc.css')             if -e 'testdoc.css';

  }

  clean();
}
```

## 1.2 ROBODoc System Tests/Handling Errors

### FUNCTION

Test wether calling ROBODoc with wrong options or input leads to the correct error messages.

### 1.2.1 Handling Errors/Error on Duplicate Options

#### FUNCTION

ROBODOc should complain about options that are specified more than once.

#### SOURCE

```
{
  add_source( "test.c", $source );
  my ($out, $err) = runrobo( qw( --src Src --doc Doc --multidoc --test --test --test) );
  print $out;
  like($out, qr/Usage/, 'Duplicate options should print usage' );
  print $err;
  like($err, qr/than\sonce/, 'and an error message' );
  clean();
}
```

### 1.2.2 Handling Errors/Error on Mutual Excluding Options

#### FUNCTION

ROBODoc should complain about options that can not be used together.

#### SOURCE

```
{
  add_source( "test.c", $source );
  my ($out, $err) = runrobo( qw(--src Src --doc Doc --multidoc --singledoc --html) );
  like($out, qr/Usage/, 'Mutual excluding options should print usage' );
  print $err;
  like($err, qr/together/, 'and an error message' );
  clean();
}
```

### 1.2.3 Handling Errors/Error on Mutual Excluding Options II

#### FUNCTION

ROBODoc should complain about options that can not be used together.

#### SOURCE

```
{
  add_source( "test.c", $source );
  my ($out, $err) = runrobo( qw(--src Src --doc Doc --multidoc --test --dbxml --html) );
  like($out, qr/Usage/, 'Mutual excluding options should print usage' );
  print $err;
  like($err, qr/together/, 'and an error message' );
  clean();
}
```

#### 1.2.4 Handling Errors/Error on Non-existing Option

##### FUNCTION

ROBODoc should complain about non-existing options.

##### SOURCE

```
{
  my ($out, $err) = runrobo( '--foobar' );
  like($out, qr/Usage/, 'Unknown option should print usage' );
  like($err, qr/Invalid/, 'and an error message' );
}
```

### 1.2.5 Handling Errors/Error on Non-existing rc file

#### FUNCTION

When given a non-existing .rc file, ROBODc should at least report the name of the .rc file.

#### SOURCE

```
{
  my ($out, $err) = runrobo( '--rc foobar.rc' );
  like($err, qr/foobar/, 'should give an error message about foobar.rc' );
}
```



### 1.2.6 Handling Errors/Header without end marker

#### FUNCTION

Test ROBODoc's response on a header without an end marker. ROBODoc should detect this.

#### SOURCE

```
{
    my $source = <<'EOF';
/****f* Test/test
* NAME
*   Test
* FUNCTION
*   Test2
* SOURCE
*/

some source

and no end of the header ....

EOF

    add_source( "test.c", $source );
    my ($out, $err) = runrobo( qw(--src Src --doc Doc --multidoc --test) );
    is( $out, '', 'no output' );
    like( $err, qr/end\smarker/, 'error about end marker' );
    clean();
}
```

### 1.2.7 Handling Errors/Headers with duplicate names

#### FUNCTION

Test ROBODoc's response to a file with two headers that have the same name. This should be reported as an error.

#### SOURCE

```
{
    my $source = <<'EOF';
/****f* Test/test
* NAME
*   Test
* FUNCTION
*   Test2
****
*/

/****f* Test/test
* NAME
*   Test
* FUNCTION
*   Test2
****
*/

EOF

    add_source( "test.c", $source );
    my ($out, $err) = runrobo( qw(--src Src --doc Doc --multidoc --test) );
    is( $out, '', 'no output' );
    like( $err, qr/already\sexists/, 'error duplicate header' );
    clean();
}
```

### 1.2.8 Handling Errors/Impossible output file

#### FUNCTION

When given a impossible output filename ROBODoc should at least report the filename.

#### SOURCE

```
{
  add_source( "test.c", $source );
  my ($out, $err) = runrobo( qw(--src Src --doc Foo/Bar/document --singledoc --html) );
  like($err, qr/document/, 'should give an error message about document' );
}
```

### 1.2.9 Handling Errors/Non-existing css file

#### FUNCTION

When given a impossible css filename ROBODoc should at least report the filename.

#### SOURCE

```
{
  add_source( "test.c", $source );
  my ($out, $err) = runrobo( qw(--src Src --doc Docs --multidoc --html --css Foo/Bar/cascade.css) );
  like($err, qr/cascade/, 'should give an error message about css file' );
}
```

### 1.3 ROBODoc System Tests/Header Test

#### FUNCTION

Tests the parsing of ROBODoc headers.

### 1.3.1 Header Test/Happy Path

#### FUNCTION

Happy Path Simple plain header. This definitely should work

#### SOURCE

```
{
    my $source = <<'EOF';
/****f* Test/test
* NAME
*   Test
* FUNCTION
*   Test2
*****
*/
EOF

    add_source( "test.c", $source );
    my ($out, $err) = runrobo( qw(--src Src --doc Doc --multidoc --test) );
    is( $out, '', 'no output' );
    is( $err, '', 'and no error' );
    clean();
}
```

### 1.3.2 Header Test/Multiple Names with Spaces

#### FUNCTION

Try several header with names that contain spaces. These should be accepted.

#### SOURCE

```
{
  my $source = <<'EOF';
/****f* Test Foo Bar/Name With Spaces, And Anotherone,
*           And One More, More
* NAME
*   Test
* FUNCTION
*   Test2
* *****
*/
EOF

  add_source( "test.c", $source );
  my ($out, $err) = runrobo( qw(--src Src --doc Doc --multidoc --test) );
  is( $out, '', 'no output' );
  is( $err, '', 'and no error' );
  my $documentation = XMLin( 'Doc/test_c.xml' );
  my $header = $documentation->{'header'};
  is ( $header->{'name'}, 'Test Foo Bar/Name With Spaces', 'Header name' );
#   clean();
}
```

### 1.3.3 Header Test/Names with Spaces

#### FUNCTION

Try a header name with spaces and some '\*' at the end. The '\*' should be ignored.

#### SOURCE

```
{
  my $source = <<'EOF';
/****f* Test Foo Bar/Name With Spaces ****
* NAME
*   Test
* FUNCTION
*   Test2
*****
*/
EOF

  add_source( "test.c", $source );
  my ($out, $err) = runrobo( qw(--src Src --doc Doc --multidoc --test) );
  is( $out, '', 'no output' );
  is( $err, '', 'and no error' );
  my $documentation = XMLin( 'Doc/test_c.xml' );
  my $header = $documentation->{'header'};
  is ( $header->{'name'}, 'Test Foo Bar/Name With Spaces', 'Header name' );
  clean();
}
```



## 1.4 ROBODoc System Tests/Wiki Formatting

### FUNCTION

Tests that test the Wiki like formatting that ROBODoc supports.

### 1.4.1 Wiki Formatting/Wiki Basics

#### FUNCTION

Test a simple header: contains three lists, some paragraphs, and some source. All should be recognized.

#### SOURCE

```
{
    my $source = <<'EOF';
/****f* Test/Test
* NAME
*
* Implements serializers for the following
* files:
* - DZB_ACG - SAP accounting file record.
* - DZB_RRP - regularoty reporting file record.
* - DZB_MVT - Exchange Position File Record.
*
*
* Implements the following
* functions:
* - S99304_SERIALIZE_DZB_ACG
* - S99304_SERIALIZE_DZB_ACG_TBL
* - S99304_SERIALIZE_DZB_MVT
* and the functions:
* - S99304_SERIALIZE_DZB_MVT_TBL
* - S99304_SERIALIZE_DZB_RRP
* - S99304_SERIALIZE_DZB_RRP_TBL
* SOURCE
*/
    test()

/*****/

EOF

add_source( "test.c", $source );
my ( $out, $err ) = runrobo(qw(--src Src --doc Doc --nopre --multidoc --test));
# expected results:
is( $out, '', 'No ouput' );
is( $err, '', '... and no error' );

my $documentation = XMLin( 'Doc/test_c.xml' );
my $header = $documentation->{'header'};
is ( $header->{'name'}, 'Test/Test', 'Header is named Test/Test' );
my $items = $header->{'item'};
ok ( exists( $items->{'NAME'} ), 'header has an item NAME' );
ok ( exists( $items->{'SOURCE'} ), 'header has an item SOURCE' );
my $body = $items->{'NAME'}->{'item_body'};

# There are paragraphs.
ok ( exists( $body->{'para'} ), 'item has paragraphs' );
```

```
# There are three lists.  
is ( scalar( @{ $body->{'list'} } ), 3, 'item has two lists' );  
clean();  
}
```

## 2 **ROBODoc/ROBOTestFrame**

### **FUNCTION**

A Perl module with a set of handy functions to create test scripts.

These function are:

- `runrobo` (2.5)
- `add_source` (2.1)
- `clean` (2.2)

## 2.1 ROBOTestFrame/add\_source

### FUNCTION

Add a single source file somewhere in Src/

### SOURCE

```
sub add_source
{
    my $filepath = shift;
    my $source    = shift;

    my $dir_name = "$src" . dirname( $filepath );

    if ( ! -e "$dir_name" ) {
        mkpath $dir_name or die "can't create $dir_name";
    }

    my $full_filepath = "$src/$filepath";
    my $file = IO::File->new(">$full_filepath") or die "Can't open $full_filepath";
    print $file $source;
    $file->close();
}
```

## 2.2 ROBOTestFrame/clean

### FUNCTION

Clean source and documentation directories.

### SOURCE

```
sub clean
{
  if ( -e $src ) {
    rmtree( $src ) or die;
  }
  if ( -e $doc ) {
    rmtree( $doc ) or die;
  }
}
```

### **2.3 ROBOTestFrame/doc**

#### **FUNCTION**

Name of the documentation directorie use to test ROBODoc.

## 2.4 ROBOTestFrame/robo

### FUNCTION

Location of the ROBODoc executable.

### SOURCE

```
my $robo = "../robodoc.exe";
```



## 2.5 ROBOTestFrame/runrobo

### FUNCTION

Run robodoc with the given set of arguments and capture all output to stdout en stderr.

### SOURCE

```
sub runrobo
{
    run( [ $robo, @_ ], \my( $in, $out, $err ) );
    return ($out, $err);
}
```

## 2.6 **ROBOTestFrame/src**

### **FUNCTION**

Name of the source directory used to test ROBODoc.

### **SOURCE**

```
my $src = "Src";
```

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